

11-04-73
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Curvature Continuity in Arbitrary Bicubic Bezier Patches

Final Report

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**Contract NAG-1-1039
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Hampton, VA 23665-5225**

(NACA-CR-112785) CURVATURE CONTINUITY IN
ARBITRARY BICUBIC BEZIER PATCHES Final
Report (Georgia Inst. of Tech.) 35 p

CSCL 12A

NR2-18683

Uncl. 6
62/56 605471

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Abstract

The following document outlines two methods for imposing interpatch curvature continuity in existing Bezier bicubic patch surfaces. Each method assumes that coordinates of the corners of the patches can not be altered but the interior Bezier control points can. Each method also preserves outer edge slope and outer corner twist derivatives. Neither method requires intersection or C0 continuity nor slope or C1 continuity at the start. A computer program for each method is given in the appendices.

Background

Computer-aided geometric design uses many forms of surface representation. Among the most popular to date are those which some use of cubic polynomials. The cubic polynomials can be easily manipulated in many instances and makes the difficult numerical problem of finding patch intersections more tractable than would some more complex functions. The cubic polynomial is also chosen since it is the minimum order polynomial which can satisfy curvature continuity constraints desirable in many applications [1]. Curvature continuity is important in many applications since the smoothness of a surface demands a small rates of change of curvature except at corners.

Given surfaces are frequently represented by patches consisting of smaller pieces of a whole surface. Each patch may be represented by a 2 dimensional array of coordinate points which lie on the surface. The designer then frequently needs to be able to faithfully interpolate between these given points. This brings in the frequent use of splines for surface representation and will be used here. However, the designer frequently does want to know all the spline details and would prefer to have a representation of the surfaces such that he may easily manipulate the shape. This can be done easily with Cubic Bezier surfaces, the control points of which locally control the shape of the surface. Hence the designer may "lock on" to one of the control points and "drag" it to a new location, causing a controllable distortion of the nearby surface. We next examine some detail of the bicubic Bezier patch.

In a given patch with $n \times m$ points, there are $(n-1) \times (m-1)$ subpatches. Each subpatch has four points at its corners. This may be all the data that the designer has to start with. If the overall patch is to be mated with other patches then the surface slope normal to the edge would likely be specified. Within each subpatch, a bicubic Bezier surface has 16 control points in a 4×4 array. The bicubic surface and all properties are completely specified by these control points since the basis functions are also specified. Four of these control points lie at the corners. Eight more lie along the edges and four are in the interior of the subpatch. Locations of the control points not on the corners control the surface curvature, slope, and position.

The Bezier representation, while simple to formulate and manipulate, does not necessarily give the user first or second derivative continuity between adjacent patches. Trying to provide such continuity by eye will be approximate at best for the slope continuity and not doable for the other. As a consequence a post processing capability is envisioned in which the user has generated the surface as close as possible to his own specifications and then his surface is modified in some minimal way to ensure slope and curvature continuity. This minimal way would most likely correspond to leaving those features intact that the designer would also choose, such as the boundary points and

particular surface points at the corners of each subpatch. Further, the outer edge slope may be important and should be kept. Thus the post processing subroutine would only change the relative positions of the subpatch interior control points and those between the subpatch corner points.

This still leaves a number of degrees of freedom all of which can be shown to be related to the manner in which the "twist" derivatives are computed. The twist derivatives are second derivatives of the components of the position vector with respect to the parameters s and t , ie. x_{st} at corners. An original method by Ferguson [1] required these twist derivatives to simply be zero. While this gives the requisite slope and curvature continuity, apparently flat spots existed at the subpatch corners. Thus, this method was not deemed suitable.

Two other methods suggest themselves. In each, nonzero twist vectors result, but only the second method specifically uses them. The methods are similar in that in each, cubic splines are first placed through all subpatch corners as will be described. They thus both seek to determine the elements of the biparametric surface cubic for each subpatch. Cubic splines through the subpatch corners determine 12 of the 16 elements. The methods differ in the next step, that of computing the remaining elements of the biparametric cubic matrices.

Analysis

Consider the large patch shown in Fig. 1. The patch consists of m subpatches in the t direction and n subpatches in the s direction. On each subpatch, there exists the 16 Bezier control points numbered 0-15. The numbering of the control points and the corresponding directions are consistent with the numbering system used by the NASA-Langley SMART program. The four on the corners are coincident with the corners of the subpatch and are to be retained.

The main idea of the procedures to be described is that slope and curvature continuity can be attained by first switching from a Bezier representation to a cubic spline representation for the surfaces. Cubic spline curves through data points in space have such continuity at all points. It is also fortunate that a rather convenient set of relations exist between the Bezier curves and cubic spline curves of the same order making it a simple matter to switch back and forth. By using cubic splines in both directions, it should be possible to effect the same for the surfaces. The biparametric cubic spline surface representation of a single subpatch surface is characterized by a 4×4 coefficient matrix. Once the 16 elements of this matrix are determined for each subpatch, the Bezier coefficients can be determined.

Thus, cubic splines are placed through all the subpatch corners, from one edge of the large patch to the other in both the t and s directions. The slope of the large patch around the edges is also retained as the extra information required of the ends of the cubic splines. Once the cubic splines are determined along the subpatch edges, 12 of the 16 matrix elements are known. This leaves 4 unknown and corresponds to not knowing the 4 interior Bezier control point locations. At this point, we describe two methods for determining these coefficients in such a manner that slope and curvature continuity are assured across subpatch boundaries.

Method 1. Splines Fit through Second Derivatives

It is well known that curvature is related to second derivatives. It is also known that the cubic splines through the subpatch corners provide second derivative continuity tangential to subpatch edges. What is not guaranteed is second derivative continuity normal to the edges. Thus, this method is based on putting cubic splines through the second derivatives of one parameter in the direction of the other, ie. putting splines through x_{tt} in the s direction. This allows the computation of the missing elements of the biparametric cubic coefficient matrix and directly assures second derivative continuity across subpatch edges. It also turns out that if splines had been placed on x_{ss} in the t direction, the same result would have been obtained. A program written in QuickBasic which performs this task is given in Appendix A.

Method 2. Twist Derivative Method

In this method, the large patch corner twist derivatives, x_{st} , are computed from the original Bezier coefficients. Next, cubic splines are placed through x_t in the s direction on the outer two s boundaries of the large patch. The original twist derivatives are used as slope end conditions for these two splines. With x_{st} now available on these two edges, they are used as the slope end conditions of cubic splines placed through x_s in the t direction. The remaining twist derivatives are then computed from these splines. Knowing the twist derivatives at each of the subpatch corners allows the completion of the biparametric cubic coefficient matrices. A QuickBasic program written to effect this computation is given in Appendix B.

Computation of the New Bezier Coefficients

Once the biparametric cubic surfaces are known from either method above, standard relationships are used to compute the new Bezier control point locations. These are then returned to the in place of the original set. The programs in the appendices perform this computation. The new set has changed all Bezier control point locations except those along the large patch edges, those immediately adjacent to the outer edges, and those at all subpatch corners.

Results

Each of the subpatches in the 3×3 patch shown in Fig. 1 were originally flat surfaces with Bezier control point locations coplanar with the subpatch edges. The second method was used to generate the new set of control points which is shown in Fig. 2. The outside edges are all still nearly flat as these were left intact in the procedure. This gives the highest curvature at the vertical intersections between the subpatches. That the second derivative continuity has been accomplished is shown in Fig. 3-8. Each of these is a contour plot of lines of constant second derivative on the large patch. It can be seen that each of the contours is continuous with no breaks. There are corners on some of them indicating a lack of C^3 continuity at these points. These occur only at subpatch edges.

References

1. Ferguson, J.C., "Multivariate Curve Interpolation," Journal ACM, Vol. 11, No. 2, Feb. 1964, pp.221-228.
2. Faux, I.D. and M.J. Pratt, Computational Geometry for Design and Manufacture, ISBN 0-85312-114-1, Ellis Horwood Ltd, West Sussex, England, 1979.

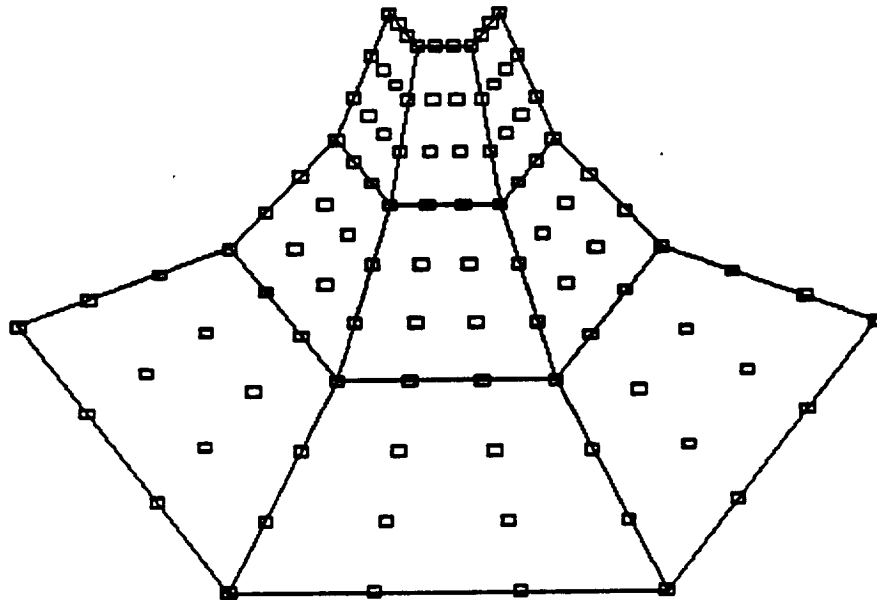


Fig. 1 3x3 large patch with flat subpatches

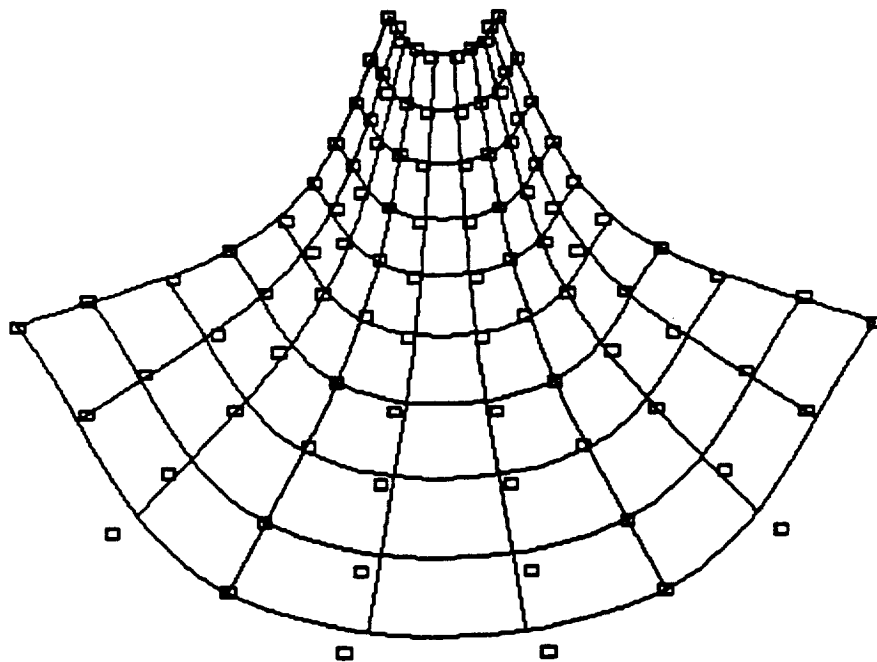


Fig. 2 New control point locations on large patch and some smoothed surface lines.

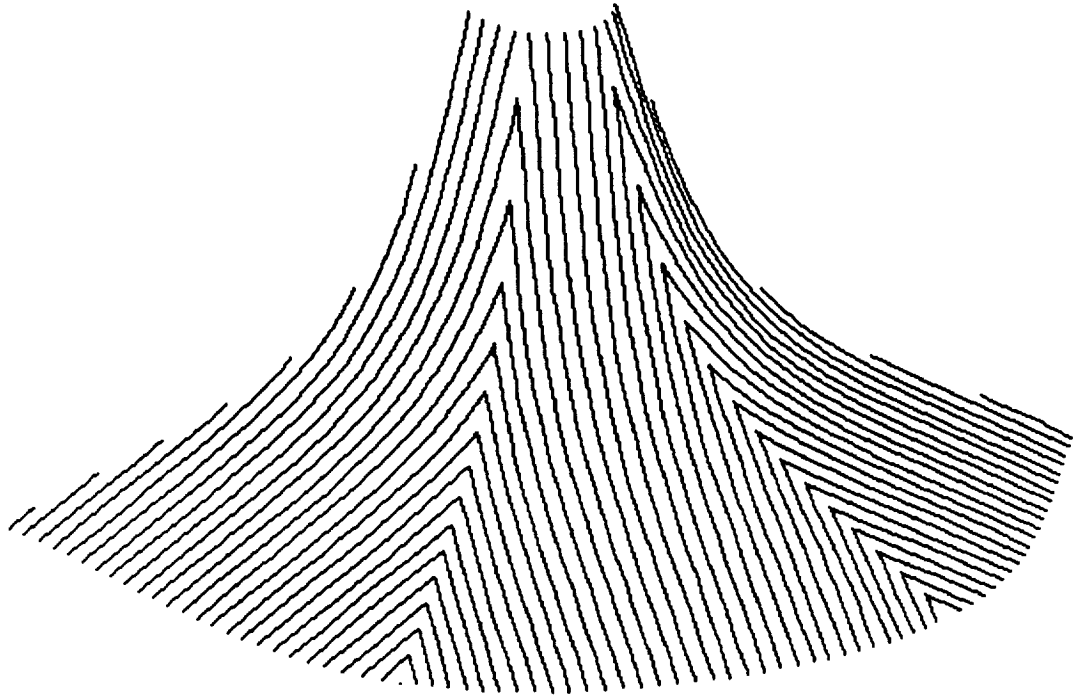


Fig. 3 x_{tt} contours

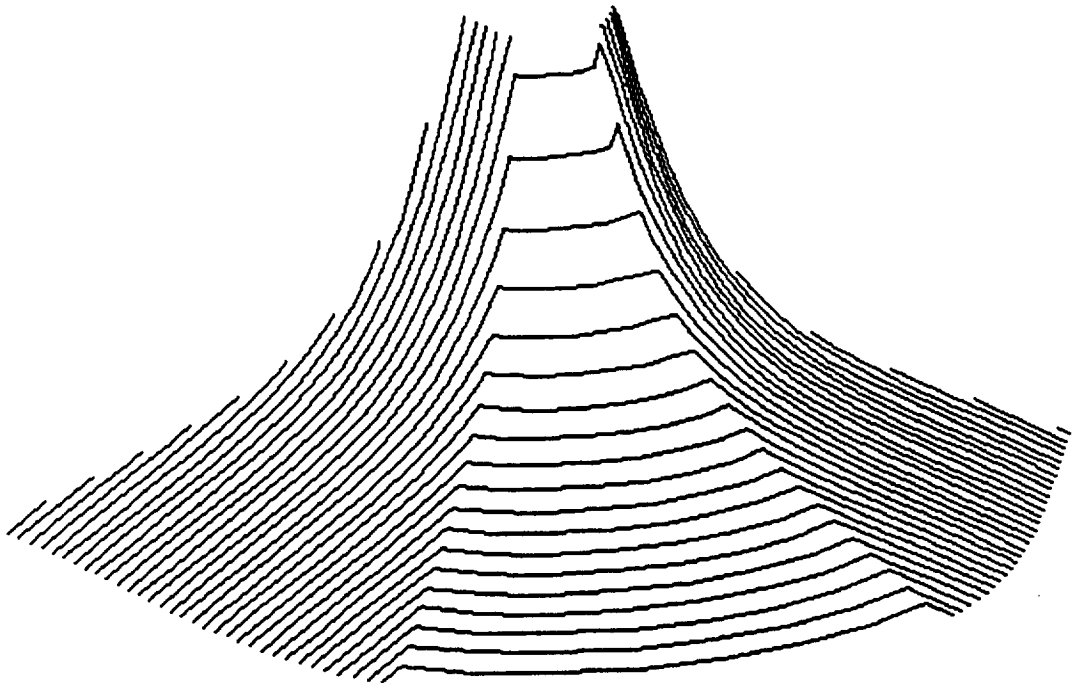


Fig. 4 y_{tt} contours

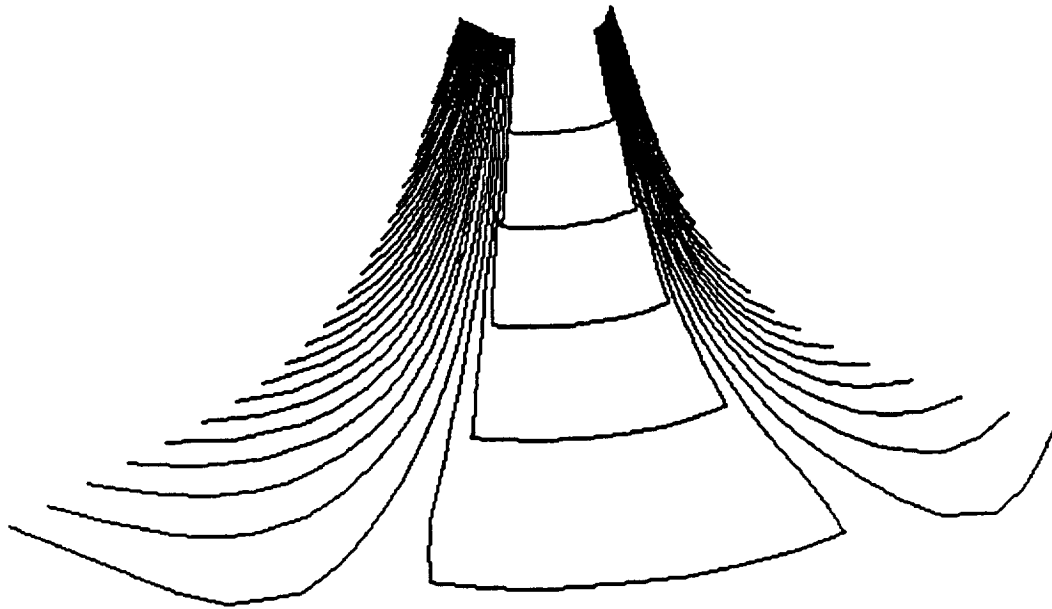


Fig. 5 z_{tt} contours

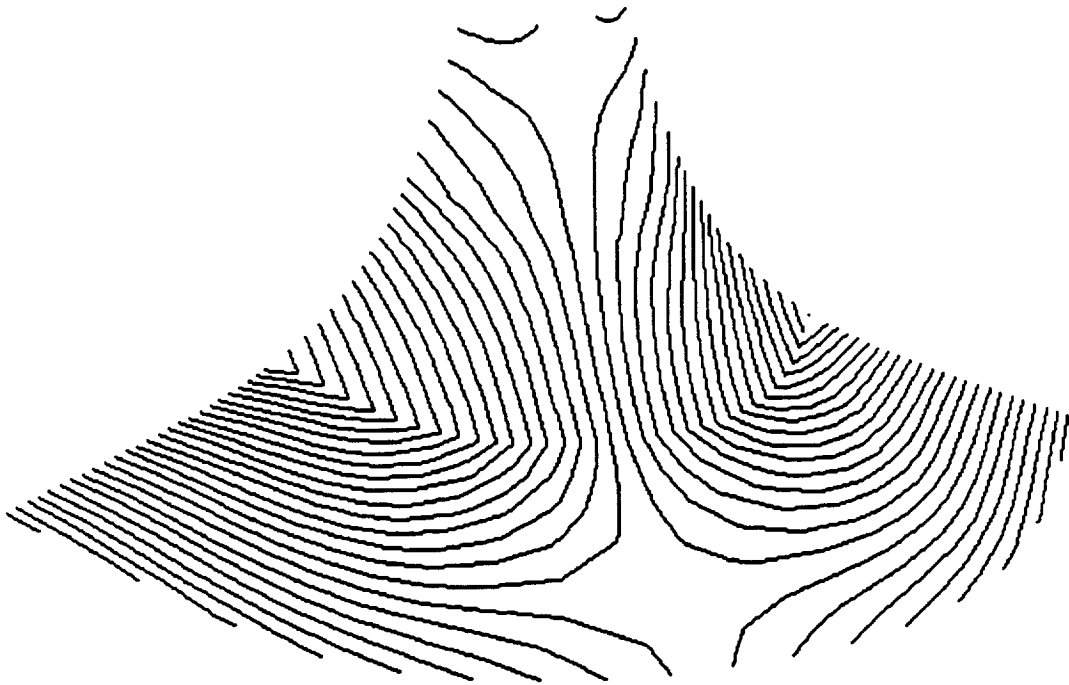


Fig. 6 x_{ss} contours

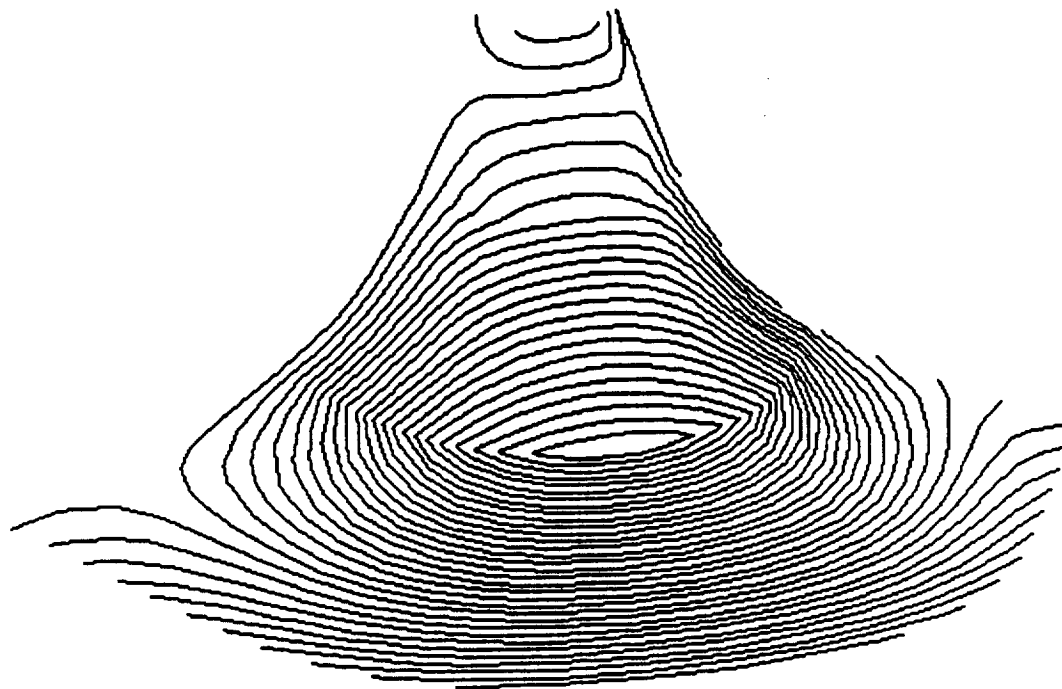


Fig. 7 y_{ss} contours

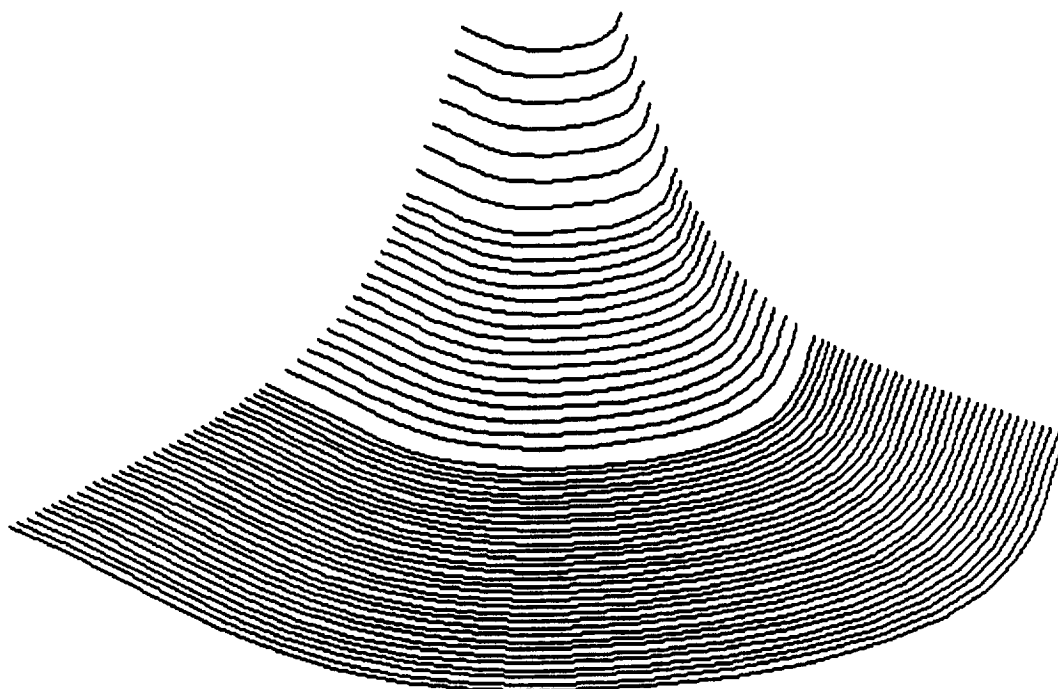


Fig. 8 z_{ss} contours

Appendix A.

Method 1. Cubic Splines through Second Derivatives

```

REM                                PROGRAM BPCS - Bi-Parametric Cubic Spline
REM-----
REM
REM    This program computes a bi-cubic interpolating function
REM    through a rectangular array of coordinate data with curvature
REM    continuity along all interior patches.  This is done by fit-
REM    ting cubic splines along rows of points in each direction.
REM    Then, the second derivatives of the interpolating functions
REM    are "splined" in the other parametric direction.
REM
REM    XX,YY,ZZ                Coordinate data
REM    X,Y,Z                  Data through which a spline is fit
REM    II,JJ                  # of coords in T-direction,S-direction
REM    N                      # of points fed to PC Spline subroutine
REM    ND                     # of space dimensions (ie. = 3 for 3D)
REM
REM    AX,BX,CX                Coeff's of splines for X from PCSSUB
REM    AY,BY,CY                Coeff's of splines for Y from PCSSUB
REM    AZ,BZ,CZ                Coeff's of splines for Z from PCSSUB
REM
REM    AXT,BXT,CXT            Coeff's of T-lines for X
REM    AYT,BYT,CYT            Coeff's of T-lines for Y
REM    AZT,BZT,CZT            Coeff's of T-lines for Z
REM
REM    AXS,BXS,CXS            Coeff's of S-lines for X
REM    AYS,BYS,CYS            Coeff's of S-lines for Y
REM    AZS,BZS,CZS            Coeff's of S-lines for Z
REM
REM    KX,KY,KZ                Coeff's of biparametric patches
REM-----
REM    DEFDBL A-Z
REM
REM    DIM XX(21,21),YY(21,21),ZZ(21,21)
REM    DIM X(21),Y(21),Z(21)
REM    DIM A(21),B(21),C(21)
REM    DIM AX(21),BX(21),CX(21)
REM    DIM AY(21),BY(21),CY(21)
REM    DIM AZ(21),BZ(21),CZ(21)
REM    DIM AXT(21,15),BXT(21,15),CXT(21,15)
REM    DIM AYT(21,15),BYT(21,15),CYT(21,15)
REM    DIM AZT(21,15),BZT(21,15),CZT(21,15)
REM    DIM AXS(21,15),BXS(21,15),CXS(21,15)
REM    DIM AYS(21,15),BYS(21,15),CYS(21,15)
REM    DIM AZS(21,15),BZS(21,15),CZS(21,15)
REM    DIM D(21),E(21),F(21)
REM    DIM XTT(21,15),YTT(21,15),ZTT(21,15)
REM    DIM XSS(21,15),YSS(21,15),ZSS(21,15)
REM    DIM XV(16,14,14),YV(16,14,14),ZV(16,14,14),CC(4)
REM    DIM KX(16,14,14),KY(16,14,14),KZ(16,14,14)
REM
REM-----
REM    USEFUL STUFF -----
REM
REM    SCREEN 9
REM    WINDOW (0,-2)-(2,5)
REM    XVP = -10
REM    YVP = 10
REM    ZVP = 10
REM    ND = 3
REM
REM-----
20 REM----- COORD DATA -----

```

```
LOCATE 13,20: INPUT "Enter choice: ",ICD
```

```
IF ICD = 1 THEN
```

```
LOCATE 15,20: INPUT "Enter data file name: ",DATNAM$
```

```
LOCATE 17,20: PRINT USING "Reading XX,YY,and ZZ from &...."; DATNAM$
```

```
OPEN DATNAM$ FOR INPUT AS #1
```

```
INPUT #1,II,JJ
```

```
LOCATE 18,20: PRINT USING "Surface has ## x ## points..."; II,JJ
```

```
XL = 10000: YL = 10000: ZL = 10000
```

```
XM = -10000: YM = -10000: ZM = -10000
```

```
FOR J = 1 TO JJ
```

```
FOR I = 1 TO II
```

```
INPUT #1,XX(I,J),YY(I,J),ZZ(I,J)
```

```
IF XX(I,J) < XL THEN XL = XX(I,J)
```

```
IF XX(I,J) > XM THEN XM = XX(I,J)
```

```
IF YY(I,J) < YL THEN YL = YY(I,J)
```

```
IF YY(I,J) > YM THEN YM = YY(I,J)
```

```
IF ZZ(I,J) < ZL THEN ZL = ZZ(I,J)
```

```
IF ZZ(I,J) > ZM THEN ZM = ZZ(I,J)
```

```
NEXT
```

```
NEXT
```

```
CLOSE #1
```

```
ELSE
```

```
LOCATE 15,20: PRINT "Generating XX,YY,and ZZ...."
```

```
II = 5
```

```
JJ = 5
```

```
LOCATE 18,20: PRINT USING "Surface has ## x ## points..."; II,JJ
```

```
XL = 10000: YL = 10000: ZL = 10000
```

```
XM = -10000: YM = -10000: ZM = -10000
```

```
FOR J = 1 TO JJ
```

```
YYY = (J - 1)/(JJ - 1)
```

```
FOR I = 1 TO II
```

```
XXX = (I - 1)/(II - 1)
```

```
XX(I,J) = XXX
```

```
YY(I,J) = YYY
```

```
REM R = (XXX - .5)^2 + (YYY - .5)^2
```

```
REM E = EXP(-3*SQR(R))
```

```
ZZ(I,J) = 4*(YYY - .5)^2 - 4*(XXX - .5)^2
```

```
IF XX(I,J) < XL THEN XL = XX(I,J)
```

```
IF XX(I,J) > XM THEN XM = XX(I,J)
```

```
IF YY(I,J) < YL THEN YL = YY(I,J)
```

```
IF YY(I,J) > YM THEN YM = YY(I,J)
```

```
IF ZZ(I,J) < ZL THEN ZL = ZZ(I,J)
```

```
IF ZZ(I,J) > ZM THEN ZM = ZZ(I,J)
```

```
NEXT
```

```
NEXT
```

```
END IF
```

```
XPL = YVP + (YVP - YL)*XVP/(XL - XVP)
```

```
XPM = YVP + (YVP - YM)*XVP/(XM - XVP)
```

```
YPL = ZVP + (ZVP - ZL)*XVP/(XL - XVP)
```

```
YPM = ZVP + (ZVP - ZM)*XVP/(XM - XVP)
```

```
DXW = XPM - XPL
```

YWM = YPM + .1*DYW

REM----- DRAW COORDS IN SPACE -----

CLS

WINDOW (XWL,YWL)-(XWM,YWM)

FOR J = 1 TO JJ

XP = YVP + (YVP - YY(1,J))*XVP/(XX(1,J) - XVP)

YP = ZVP + (ZVP - ZZ(1,J))*XVP/(XX(1,J) - XVP)

PSET (XP,YP)

FOR I = 2 TO II

XP = YVP + (YVP - YY(I,J))*XVP/(XX(I,J) - XVP)

YP = ZVP + (ZVP - ZZ(I,J))*XVP/(XX(I,J) - XVP)

LINE -(XP,YP),11

NEXT

NEXT

FOR I = 1 TO II

XP = YVP + (YVP - YY(I,1))*XVP/(XX(I,1) - XVP)

YP = ZVP + (ZVP - ZZ(I,1))*XVP/(XX(I,1) - XVP)

PSET (XP,YP)

FOR J = 2 TO JJ

XP = YVP + (YVP - YY(I,J))*XVP/(XX(I,J) - XVP)

YP = ZVP + (ZVP - ZZ(I,J))*XVP/(XX(I,J) - XVP)

LINE -(XP,YP),11

NEXT

NEXT

DO: LOOP WHILE INKEY\$ = ""

REM----- GET PC SPLINES THROUGH THE DATA -----

REM----- T-LINES (I-DIRECTION)

CLS

LOCATE 9,20: PRINT "Computing splines in T-direction.."

LOCATE 10,20: PRINT USING " (there are ## pts on each T line)"; II

LOCATE 12,20: PRINT "Which end condition do you want:"

LOCATE 13,20: PRINT " 1 - Natural (x'',y'',z'' = 0)"

LOCATE 14,20: PRINT " 2 - Periodic (matched slopes)"

LOCATE 15,20: PRINT " 3 - Slope (specified at ends)"

LOCATE 16,20: INPUT "Enter choice: ",ICE

IF ICE = 1 THEN CASE\$ = "NATURAL"

IF ICE = 2 THEN CASE\$ = "PERIODIC"

IF ICE = 3 THEN CASE\$ = "SLOPE"

N = II

FOR J = 1 TO JJ

LOCATE 20,20: PRINT USING "Now doing T-Line ##"; J

FOR I = 1 TO II

X(I) = XX(I,J)

Y(I) = YY(I,J)

Z(I) = ZZ(I,J)

NEXT

GOSUB 1000

FOR I = 1 TO II - 1

AXT(I,J) = AX(I)

```

BYT(I,J) = BY(I)
CYT(I,J) = CY(I)

AZT(I,J) = AZ(I)
BZT(I,J) = BZ(I)
CZT(I,J) = CZ(I)

IF J = JJ GOTO 70

KX(4,I,J) = AX(I)
KX(8,I,J) = BX(I)
KX(12,I,J) = CX(I)

KY(4,I,J) = AY(I)
KY(8,I,J) = BY(I)
KY(12,I,J) = CY(I)

KZ(4,I,J) = AZ(I)
KZ(8,I,J) = BZ(I)
KZ(12,I,J) = CZ(I)

```

70 NEXT

 NEXT

REM----- S-LINES (J-DIRECTION)

CLS

```

LOCATE 9,20: PRINT "Computing splines in S-direction.."
LOCATE 10,20: PRINT USING " (there are ## pts on each S line)"; JJ
LOCATE 12,20: PRINT "Which end condition do you want:"
LOCATE 13,20: PRINT " 1 - Natural (x'',y'',z'' = 0)"
LOCATE 14,20: PRINT " 2 - Periodic (matched slopes)"
LOCATE 15,20: PRINT " 3 - Slope (specified at ends)"
LOCATE 16,20: INPUT "Enter choice: ",ICE

```

```

IF ICE = 1 THEN CASE$ = "NATURAL"
IF ICE = 2 THEN CASE$ = "PERIODIC"
IF ICE = 3 THEN CASE$ = "SLOPE"

```

N = JJ

FOR I = 1 TO II

 LOCATE 20,20: PRINT USING "Now doing S-Line ##"; I

 FOR J = 1 TO JJ

 X(J) = XX(I,J)

 Y(J) = YY(I,J)

 Z(J) = ZZ(I,J)

 NEXT

GOSUB 1000

FOR J = 1 TO JJ - 1

 AXS(I,J) = AX(J)

 BXS(I,J) = BX(J)

 CXS(I,J) = CX(J)

 AYS(I,J) = AY(J)

 BYS(I,J) = BY(J)

 CYS(I,J) = CY(J)

IF I = II GOTO 76

KX(13,I,J) = AX(J)
KX(14,I,J) = BX(J)
KX(15,I,J) = CX(J)

KY(13,I,J) = AY(J)
KY(14,I,J) = BY(J)
KY(15,I,J) = CY(J)

KZ(13,I,J) = AZ(J)
KZ(14,I,J) = BZ(J)
KZ(15,I,J) = CZ(J)

76 NEXT

 NEXT

REM----- NOW DRAW THE CUBIC SPLINES -----

CLS

XWL = XWL + .3*DXW
XWM = XWM - .3*DXW
YWL = YWL + .3*DYW
YWM = YWM - .3*DYW

REM WINDOW (XWL,YWL)-(XWM,YWM)

FOR J = 1 TO JJ

 FOR I = 1 TO II - 1

 XP = YVP + (YVP - YY(I,J))*XVP/(XX(I,J) - XVP)

 YP = ZVP + (ZVP - ZZ(I,J))*XVP/(XX(I,J) - XVP)

 PSET (XP,YP)

 FOR T = 0 TO 1 STEP .099

 XXX = XX(I,J) + ((AXT(I,J)*T + BXT(I,J))*T + CXT(I,J))*T

 YYY = YY(I,J) + ((AYT(I,J)*T + BYT(I,J))*T + CYT(I,J))*T

 ZZZ = ZZ(I,J) + ((AZT(I,J)*T + BZT(I,J))*T + CZT(I,J))*T

 XP = YVP + (YVP - YYY)*XVP/(XXX - XVP)

 YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

 LINE -(XP,YP),11

 NEXT

 NEXT

NEXT

FOR I = 1 TO II

 FOR J = 1 TO JJ - 1

 XP = YVP + (YVP - YY(I,J))*XVP/(XX(I,J) - XVP)

 YP = ZVP + (ZVP - ZZ(I,J))*XVP/(XX(I,J) - XVP)

 PSET (XP,YP)

 FOR S = 0 TO 1 STEP .099

 XXX = XX(I,J) + ((AXS(I,J)*S + BXS(I,J))*S + CXS(I,J))*S

 YYY = YY(I,J) + ((AYS(I,J)*S + BYS(I,J))*S + CYS(I,J))*S

 ZZZ = ZZ(I,J) + ((AZS(I,J)*S + BZS(I,J))*S + CZS(I,J))*S

 XP = YVP + (YVP - YYY)*XVP/(XXX - XVP)

 YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

 LINE -(XP,YP),11

 NEXT

 NEXT

NEXT

DO: LOOP WHILE INKEY\$ = ""

REM----- S-DIRECTION FOR Xtt

```
FOR J = 1 TO JJ
  XTT(II,J) = 6*AXT(II - 1,J) + 2*BXT(II - 1,J)
  YTT(II,J) = 6*AYT(II - 1,J) + 2*BYT(II - 1,J)
  ZTT(II,J) = 6*AZT(II - 1,J) + 2*BZT(II - 1,J)
  FOR I = 1 TO II - 1
    XTT(I,J) = 2*BXT(I,J)
    YTT(I,J) = 2*BYT(I,J)
    ZTT(I,J) = 2*BZT(I,J)
  NEXT
NEXT
```

```
FOR I = 1 TO II
  FOR J = 1 TO JJ
    X(J) = XTT(I,J)
    Y(J) = YTT(I,J)
    Z(J) = ZTT(I,J)
  NEXT
```

GOSUB 1000

```
FOR J = 1 TO JJ - 1
```

```
  IF I = II GOTO 200
```

```
  KX(5,I,J) = .5*AX(J)
  KX(6,I,J) = .5*BX(J)
  KX(7,I,J) = .5*CX(J)
```

```
  KY(5,I,J) = .5*AY(J)
  KY(6,I,J) = .5*BY(J)
  KY(7,I,J) = .5*CY(J)
```

```
  KZ(5,I,J) = .5*AZ(J)
  KZ(6,I,J) = .5*BZ(J)
  KZ(7,I,J) = .5*CZ(J)
```

```
  IF I = 1 GOTO 210
```

```
200  KX(1,I - 1,J) = (AX(J) - 2*KX(5,I - 1,J))/6
     KX(2,I - 1,J) = (BX(J) - 2*KX(6,I - 1,J))/6
     KX(3,I - 1,J) = (CX(J) - 2*KX(7,I - 1,J))/6
```

```
     KY(1,I - 1,J) = (AY(J) - 2*KY(5,I - 1,J))/6
     KY(2,I - 1,J) = (BY(J) - 2*KY(6,I - 1,J))/6
     KY(3,I - 1,J) = (CY(J) - 2*KY(7,I - 1,J))/6
```

```
     KZ(1,I - 1,J) = (AZ(J) - 2*KZ(5,I - 1,J))/6
     KZ(2,I - 1,J) = (BZ(J) - 2*KZ(6,I - 1,J))/6
     KZ(3,I - 1,J) = (CZ(J) - 2*KZ(7,I - 1,J))/6
```

```
210  NEXT
     NEXT
```

REM----- GET REMAINDER OF THE K'S -----

```
FOR J = 1 TO JJ - 1
  FOR I = 1 TO II - 1
```

```
    KX(9,I,J) = AXS(I + 1,J) - AXS(I,J) - KX(1,I,J) - KX(5,I,J)
    KX(10,I,J) = BXS(I + 1,J) - BXS(I,J) - KX(2,I,J) - KX(6,I,J)
```


KY(11,I,J) = CYS(I + 1,J) - CYS(I,J) - KY(3,I,J) - KY(7,I,J)

KZ(9,I,J) = AZS(I + 1,J) - AZS(I,J) - KZ(1,I,J) - KZ(5,I,J)

KZ(10,I,J) = BZS(I + 1,J) - BZS(I,J) - KZ(2,I,J) - KZ(6,I,J)

KZ(11,I,J) = CZS(I + 1,J) - CZS(I,J) - KZ(3,I,J) - KZ(7,I,J)

NEXT

NEXT

REM----- NOW DRAW SOME LINES IN SOME PATCHES -----

DX = .01

DY = .02

NODRW = 1

IF NODRW = 1 GOTO 450

REM----- PATCH IP,JP

SCR = 1

FOR JP = 1 TO JJ - 1

FOR IP = 1 TO II - 1

FOR S = .25 TO .76 STEP .25

FOR T = 0 TO 1.01 STEP .05

XXX = XX(IP,JP)

YYY = YY(IP,JP)

ZZZ = ZZ(IP,JP)

FOR JT = 0 TO 3

TP = T^(3 - JT)

FOR JS = 0 TO 3

SP = S^(3 - JS)

K = (JS + 1) + 4*JT

IF K > 15 GOTO 300

XXX = XXX + KX(K,IP,JP)*TP*SP

YYY = YYY + KY(K,IP,JP)*TP*SP

ZZZ = ZZZ + KZ(K,IP,JP)*TP*SP

NEXT

NEXT

300

XP = YVP + (YVP - YYY)*XVP/(XXX - XVP)

YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

IF T = 0 THEN PSET (XP,YP)

LINE -(XP,YP),SCR

NEXT

NEXT

FOR T = .25 TO .76 STEP .25

FOR S = 0 TO 1.01 STEP .05

XXX = XX(IP,JP)

YYY = YY(IP,JP)

ZZZ = ZZ(IP,JP)

FOR JT = 0 TO 3

TP = T^(3 - JT)

FOR JS = 0 TO 3

SP = S^(3 - JS)

K = (JS + 1) + 4*JT

```

        NEXT
    NEXT

320      XP = YVP + (YVP - YYY)*XVP/(XXX - XVP)
        YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)
        IF S = 0 THEN PSET (XP,YP)
        LINE -(XP,YP),SCR

    NEXT
NEXT

NEXT
NEXT

DO: LOOP WHILE INKEY$ = ""

450 REM----- NOW GET BEZIER CONTROL POINTS -----
REM----- CC -----

    NO = 4
    NF = 1
    FOR IP = 1 TO NO - 1
        NF = NF*IP
    NEXT
    FOR IP = 0 TO NO - 1
        IFC = 1
        FOR JP = 1 TO IP
            IFC = IFC*JP
        NEXT
        FF = 1
        FOR JP = 1 TO NO - IP - 1
            FF = FF*JP
        NEXT
        CC(IP + 1) = NF/(IFC*FF)
    NEXT

REM----- CONTROL POINTS
    FOR J = 1 TO JJ
        FOR I = 1 TO II
            PRINT USING "Computing bazier control points for ##,##..."; I,J

REM----- CORNERS

        XV(0,I,J) = XX(I,J)
        YV(0,I,J) = YY(I,J)
        ZV(0,I,J) = ZZ(I,J)

        XV(3,I,J) = XX(I + 1,J)
        YV(3,I,J) = YY(I + 1,J)
        ZV(3,I,J) = ZZ(I + 1,J)

        XV(12,I,J) = XX(I,J + 1)
        YV(12,I,J) = YY(I,J + 1)
        ZV(12,I,J) = ZZ(I,J + 1)

        XV(15,I,J) = XX(I + 1,J + 1)
        YV(15,I,J) = YY(I + 1,J + 1)
        ZV(15,I,J) = ZZ(I + 1,J + 1)

REM----- ON SIDE 1 (S=0)

        XV(1,I,J) = XV(0,I,J) + CXT(I,J)/3

```

DY1 = 3*AYT(I,J) + 2*BYT(I,J) + CYT(I,J)
DZ1 = 3*AZT(I,J) + 2*BZT(I,J) + CZT(I,J)

XV(2,I,J) = XV(3,I,J) - DX1/3
YV(2,I,J) = YV(3,I,J) - DY1/3
ZV(2,I,J) = ZV(3,I,J) - DZ1/3

REM----- ON SIDE 2 (S=1)

XV(13,I,J) = XV(12,I,J) + CXT(I,J + 1)/3
YV(13,I,J) = YV(12,I,J) + CYT(I,J + 1)/3
ZV(13,I,J) = ZV(12,I,J) + CZT(I,J + 1)/3

DX1 = 3*AXT(I,J + 1) + 2*BXT(I,J + 1) + CXT(I,J + 1)
DY1 = 3*AYT(I,J + 1) + 2*BYT(I,J + 1) + CYT(I,J + 1)
DZ1 = 3*AZT(I,J + 1) + 2*BZT(I,J + 1) + CZT(I,J + 1)

XV(14,I,J) = XV(15,I,J) - DX1/3
YV(14,I,J) = YV(15,I,J) - DY1/3
ZV(14,I,J) = ZV(15,I,J) - DZ1/3

REM----- ON SIDE 3 (T=0)

XV(4,I,J) = XV(0,I,J) + CXS(I,J)/3
YV(4,I,J) = YV(0,I,J) + CYS(I,J)/3
ZV(4,I,J) = ZV(0,I,J) + CZS(I,J)/3

DX1 = 3*AXS(I,J) + 2*BXS(I,J) + CXS(I,J)
DY1 = 3*AYS(I,J) + 2*BYS(I,J) + CYS(I,J)
DZ1 = 3*AZS(I,J) + 2*BZS(I,J) + CZS(I,J)

XV(8,I,J) = XV(12,I,J) - DX1/3
YV(8,I,J) = YV(12,I,J) - DY1/3
ZV(8,I,J) = ZV(12,I,J) - DZ1/3

REM----- ON SIDE 4 (T=1)

XV(7,I,J) = XV(3,I,J) + CXS(I + 1,J)/3
YV(7,I,J) = YV(3,I,J) + CYS(I + 1,J)/3
ZV(7,I,J) = ZV(3,I,J) + CZS(I + 1,J)/3

DX1 = 3*AXS(I + 1,J) + 2*BXS(I + 1,J) + CXS(I + 1,J)
DY1 = 3*AYS(I + 1,J) + 2*BYS(I + 1,J) + CYS(I + 1,J)
DZ1 = 3*AZS(I + 1,J) + 2*BZS(I + 1,J) + CZS(I + 1,J)

XV(11,I,J) = XV(15,I,J) - DX1/3
YV(11,I,J) = YV(15,I,J) - DY1/3
ZV(11,I,J) = ZV(15,I,J) - DZ1/3

REM----- INTERIOR POINTS

REM----- POINT 5

XST = KX(11,I,J)
YST = KY(11,I,J)
ZST = KZ(11,I,J)

XV(5,I,J) = XV(1,I,J) + XV(4,I,J) - XV(0,I,J) + XST/9
YV(5,I,J) = YV(1,I,J) + YV(4,I,J) - YV(0,I,J) + YST/9
ZV(5,I,J) = ZV(1,I,J) + ZV(4,I,J) - ZV(0,I,J) + ZST/9

REM----- POINT 6

```

XV(6,I,J) = XV(2,I,J) + XV(7,I,J) - XV(3,I,J) - XST/9
YV(6,I,J) = YV(2,I,J) + YV(7,I,J) - YV(3,I,J) - YST/9
ZV(6,I,J) = ZV(2,I,J) + ZV(7,I,J) - ZV(3,I,J) - ZST/9

```

REM----- POINT 9

```

XST = 3*KX(9,I,J) + 2*KX(10,I,J) + KX(11,I,J)
YST = 3*KY(9,I,J) + 2*KY(10,I,J) + KY(11,I,J)
ZST = 3*KZ(9,I,J) + 2*KZ(10,I,J) + KZ(11,I,J)

XV(9,I,J) = XV(8,I,J) + XV(13,I,J) - XV(12,I,J) - XST/9
YV(9,I,J) = YV(8,I,J) + YV(13,I,J) - YV(12,I,J) - YST/9
ZV(9,I,J) = ZV(8,I,J) + ZV(13,I,J) - ZV(12,I,J) - ZST/9

```

REM----- POINT 10

```

XST = XST + 9*KX(1,I,J) + 6*(KX(2,I,J) + KX(5,I,J))
XST = XST + 4*KX(6,I,J) + 3*KX(3,I,J) + 2*KX(7,I,J)
YST = YST + 9*KY(1,I,J) + 6*(KY(2,I,J) + KY(5,I,J))
YST = YST + 4*KY(6,I,J) + 3*KY(3,I,J) + 2*KY(7,I,J)
ZST = ZST + 9*KZ(1,I,J) + 6*(KZ(2,I,J) + KZ(5,I,J))
ZST = ZST + 4*KZ(6,I,J) + 3*KZ(3,I,J) + 2*KZ(7,I,J)

XV(10,I,J) = XV(11,I,J) + XV(14,I,J) - XV(15,I,J) + XST/9
YV(10,I,J) = YV(11,I,J) + YV(14,I,J) - YV(15,I,J) + YST/9
ZV(10,I,J) = ZV(11,I,J) + ZV(14,I,J) - ZV(15,I,J) + ZST/9

```

NEXT

NEXT

REM----- DRAW CONTROL POINTS -----

REM CLS

DX = .02

DY = .03

FOR J = 1 TO JJ

FOR I = 1 TO II

FOR IBP = 0 TO 15

XXX = XV(IBP,I,J)

YYY = YV(IBP,I,J)

ZZZ = ZV(IBP,I,J)

XP = YVP + (YVP - YYY)*XVP/(XXX - XVP)

YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

LINE (XP + DX,YP + DY)-(XP - DX,YP - DY),11,B

NEXT

FOR IBP = 0 TO 3

FOR JBP = 0 TO 3

IB = IBP + JBP*4

XXX = XV(IB,I,J)

YYY = YV(IB,I,J)

ZZZ = ZV(IB,I,J)

XP = YVP + (YVP - YYY)*XVP/(XXX - XVP)

YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

IF JBP = 0 THEN PSET (XP,YP)

LINE -(XP,YP),11

NEXT

NEXT

FOR JBP = 0 TO 3

FOR IBP = 0 TO 3

IB = IBP + JBP*4

```

        YP = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)
        IF IBP = 0 THEN PSET (XP,YP)
        LINE -(XP,YP),11

```

```

    NEXT

```

```

  NEXT

```

```

NEXT

```

```

NEXT

```

```

REM----- NOW FILL IN SURFACE -----

```

```

FOR J = 1 TO JJ

```

```

  FOR I = 1 TO II

```

```

    NLP = 11

```

```

    FOR S = .25 TO .76 STEP .25

```

```

      FOR IP = 1 TO NLP

```

```

        T = (IP - 1)/(NLP - 1)

```

```

        XXX = XV(0,I - 1,J - 1)

```

```

        YYY = YV(0,I - 1,J - 1)

```

```

        ZZZ = ZV(0,I - 1,J - 1)

```

```

        FOR L1 = 0 TO 3

```

```

          L = L1 + 1

```

```

          B2 = CC(L)*S^(L - 1)*(1 - S)^(NO - L)

```

```

          FOR K1 = 0 TO 3

```

```

            K = K1 + 1

```

```

            IBP = K1 + L1*4

```

```

            B1 = CC(K)*T^(K - 1)*(1 - T)^(NO - K)

```

```

            XXX = XXX + B1*B2*XV(IBP,I,J)

```

```

            YYY = YYY + B1*B2*YV(IBP,I,J)

```

```

            ZZZ = ZZZ + B1*B2*ZV(IBP,I,J)

```

```

          NEXT

```

```

        NEXT

```

```

        XD = YVP + (YVP - YYY)*XVP/(XXX - XVP)

```

```

        YD = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

```

```

        IF IP = 1 THEN PSET (XD,YD)

```

```

        LINE -(XD,YD),10

```

```

      NEXT

```

```

    NEXT

```

```

  FOR T = .25 TO .76 STEP .25

```

```

    FOR IP = 1 TO NLP

```

```

      S = (IP - 1)/(NLP - 1)

```

```

      XXX = XV(0,I - 1,J - 1)

```

```

      YYY = YV(0,I - 1,J - 1)

```

```

      ZZZ = ZV(0,I - 1,J - 1)

```

```

      FOR L1 = 0 TO 3

```

```

        L = L1 + 1

```

```

        B2 = CC(L)*S^(L - 1)*(1 - S)^(NO - L)

```

```

        FOR K1 = 0 TO 3

```

```

          K = K1 + 1

```

```

          IBP = K1 + L1*4

```

```

          B1 = CC(K)*T^(K - 1)*(1 - T)^(NO - K)

```

```

          XXX = XXX + B1*B2*XV(IBP,IP,JP)

```

```

          YYY = YYY + B1*B2*YV(IBP,IP,JP)

```

```

          ZZZ = ZZZ + B1*B2*ZV(IBP,IP,JP)

```

```

        NEXT

```

```

      NEXT

```

```

      XD = YVP + (YVP - YYY)*XVP/(XXX - XVP)

```

```

      YD = ZVP + (ZVP - ZZZ)*XVP/(XXX - XVP)

```

```

      IF IP = 1 THEN PSET (XD,YD)

```

```

      LINE -(XD,YD),10

```

```

    NEXT

```

```

  NEXT

```

END

```
1000 REM----- PC SPLINE SUBROUTINE -----
REM
REM      This subroutine takes the N coordinates in the arrays
REM      X,Y,and Z,and generates the coefficients AX,BX,CX,AY,
REM      BY,CY,AZ,BZ,CZ of the corresponding cubic spline through
REM      the data.
REM
REM-----
REM----- SET UP MATRIX -----
```

T1 = TIMER

FOR KKK = 1 TO ND

FOR IT = 2 TO N - 2

C(IT) = 1

B(IT) = 4

A(IT) = 1

NEXT

REM----- RHS

X(0) = X(N): Y(0) = Y(N): Z(0) = Z(N)

FOR IT = 1 TO N - 1

IF KKK = 1 THEN

DD = X(IT + 1) - 2*X(IT) + X(IT - 1)

ELSEIF KKK = 2 THEN

DD = Y(IT + 1) - 2*Y(IT) + Y(IT - 1)

ELSE

DD = Z(IT + 1) - 2*Z(IT) + Z(IT - 1)

END IF

D(IT) = 3*DD

NEXT

REM----- CASE\$ = "NATURAL" -----

IF CASE\$ = "NATURAL" THEN

B(1) = 1

A(1) = 0

D(1) = 0

C(N - 1) = 1

B(N - 1) = 4

GOTO 2040

END IF

REM----- CASE\$ = "PERIODIC" -----

IF CASE\$ = "PERIODIC" THEN

B(1) = 4

A(1) = 1

F(1) = 1

E(1) = 1

C(N - 1) = 1

B(N - 1) = 4

FOR IT = 2 TO N - 1

E(IT) = 0

F(IT) = 0

REM----- CASE\$ = "SLOPE" -----

IF CASE\$ = "SLOPE" THEN

END IF

2040 REM----- SOLVE MATRIX -----

IF CASE\$ = "PERIODIC" THEN

GOSUB 2100

ELSE

GOSUB 2000

END IF

REM----- NOW GET COEFFS -----

IF KKK = 1 THEN

FOR IT = 1 TO N - 1

BX(IT) = D(IT)

NEXT

FOR IT = 1 TO N - 2

AX(IT) = (BX(IT + 1) - BX(IT))/3#

CX(IT) = X(IT + 1) - X(IT) - AX(IT) - BX(IT)

NEXT

CX(N - 1) = 3*AX(N - 2) + 2*BX(N - 2) + CX(N - 2)

AX(N - 1) = X(N) - BX(N - 1) - CX(N - 1) - X(N - 1)

ELSEIF KKK = 2 THEN

FOR IT = 1 TO N - 1

BY(IT) = D(IT)

NEXT

FOR IT = 1 TO N - 2

AY(IT) = (BY(IT + 1) - BY(IT))/3#

CY(IT) = Y(IT + 1) - Y(IT) - AY(IT) - BY(IT)

NEXT

CY(N - 1) = 3*AY(N - 2) + 2*BY(N - 2) + CY(N - 2)

AY(N - 1) = Y(N) - BY(N - 1) - CY(N - 1) - Y(N - 1)

ELSE

FOR IT = 1 TO N - 1

BZ(IT) = D(IT)

NEXT

FOR IT = 1 TO N - 2

AZ(IT) = (BZ(IT + 1) - BZ(IT))/3#

CZ(IT) = Z(IT + 1) - Z(IT) - AZ(IT) - BZ(IT)

NEXT

CZ(N - 1) = 3*AZ(N - 2) + 2*BZ(N - 2) + CZ(N - 2)

AZ(N - 1) = Z(N) - BZ(N - 1) - CZ(N - 1) - Z(N - 1)

END IF

NEXT

T2 = TIMER

RETURN

END

2000 REM----- SUBROUTINE TSOLV -----

FOR IT = 2 TO N - 1

CBI = C(IT)/B(IT - 1)

```

D(N - 1) = D(N - 1)/B(N - 1)

FOR IR = 2 TO N - 1
  IT = N - IR + 1
  D(IT) = (D(IT) - A(IT)*D(IT + 1))/B(IT)
NEXT

RETURN

```

```

2100 REM----- SUBROUTINE TSOLVP -----
REM
REM   This routine is used for periodic tridiagonal systems
REM
REM-----

```

```

FOR IT = 2 TO N - 2
  CBI = C(IT)/B(IT - 1)
  B(IT) = B(IT) - CBI*A(IT - 1)
  D(IT) = D(IT) - CBI*D(IT - 1)
  EBI = E(IT - 1)/B(IT - 1)
  E(IT) = E(IT) - EBI*A(IT - 1)
  F(IT) = F(IT) - EBI*F(IT - 1)
  D(N - 1) = D(N - 1) - EBI*D(IT - 1)
NEXT

CBI = C(N - 2)/B(N - 3)
B(N - 2) = B(N - 2) - CBI*A(N - 3)
A(N - 2) = A(N - 2) - CBI*F(N - 3)
D(N - 2) = D(N - 2) - CBI*D(N - 3)
EBI = E(N - 3)/B(N - 3)
C(N - 1) = C(N - 1) - EBI*A(N - 3)
B(N - 1) = B(N - 1) - EBI*F(N - 3)
D(N - 1) = D(N - 1) - EBI*D(N - 3)
CBI = C(N - 1)/B(N - 2)
B(N - 1) = B(N - 1) - CBI*A(N - 2)
D(N - 1) = D(N - 1) - CBI*D(N - 2)
F(N - 1) = 0
F(N - 2) = 0

D(N) = D(N)/B(N)

FOR IR = 2 TO N
  IT = N - IR + 1
  D(IT) = (D(IT) - A(IT)*D(IT + 1) - F(IT)*D(N))/B(IT)
NEXT

RETURN

```


Appendix B.

Method 2. Twist Derivative Method

```

REM          PROGRAM BPCS4-Bi-Parametric Cubic Spline V.4
REM-----
REM
REM          This program replaces an array of Cubic Bezier patch
REM          control points with another set which possess gradient and
REM          curvature continuity across all patch boundaries.
REM          This is done by fitting cubic splines along rows of
REM          points in each direction. This provides C2 continuity along
REM          patch boundaries. Twist derivatives are found on every corner
REM          by fitting splines through the t-derivative of the cubics in
REM          the s-direction.
REM
REM          V.4 No graphics version.
REM
REM          NPT          # of patches in the t-direction
REM          NPS          # of patches in the s-direction
REM
REM          N            # of points fed to PC Spline subroutine
REM          ND           # of space dimensions (ie. = 3 for 3D)
REM
REM          XV,YV,ZV     Bezier Control point coordinates
REM          XX,YY,ZZ      Coordinate data from input patch corners
REM          X,Y,Z         Data through which a spline is fit
REM          II,JJ         # of coords in T-direction,S-direction
REM                      (II = NPT+1,JJ = NPS+1)
REM
REM          AX,BX,CX      Coeff's of splines for X from PCSSUB
REM          AY,BY,CY      Coeff's of splines for Y from PCSSUB
REM          AZ,BZ,CZ      Coeff's of splines for Z from PCSSUB
REM
REM          FX,FY,FZ      Coeff's of tensor-product matrix
REM-----
REM
DEFDBL A-H,O-Z
DEFINT I-N

ID = 16: JD = 7: KD = 7
DIM XX(ID,JD),YY(JD,KD),ZZ(ID,JD)
DIM X(ID),Y(JD),Z(KD)
DIM A(ID),B(ID),C(ID)
DIM AX(ID),BX(ID),CX(ID)
DIM AY(JD),BY(JD),CY(JD)
DIM AZ(KD),BZ(KD),CZ(KD)
DIM XV(ID,JD,KD),YV(ID,JD,KD),ZV(ID,JD,KD)
DIM FX(ID,JD,KD),FY(ID,JD,KD),FZ(ID,JD,KD)

REM----- USEFUL STUFF -----
REM
ND = 3

REM----- COORD DATA -----
REM
DATNAM$ = "PATCHES"
PRINT USING "Reading Bezier control points from &...."; DATNAM$

OPEN DATNAM$ FOR INPUT AS #1
INPUT #1,NPT,NPS

PRINT USING "There are ## x ## patches..."; NPT,NPS

FOR J = 1 TO NPS

```

NEXT
NEXT

CLOSE #1

II = NPT + 1
JJ = NPS + 1

REM----- GET TWIST VECTORS ON OUTERMOST CORNERS -----

REM----- Corner at 0,0

FX(10,1,1) = 9*(XV(0,1,1) - XV(1,1,1) - XV(4,1,1) + XV(5,1,1))
FY(10,1,1) = 9*(YV(0,1,1) - YV(1,1,1) - YV(4,1,1) + YV(5,1,1))
FZ(10,1,1) = 9*(ZV(0,1,1) - ZV(1,1,1) - ZV(4,1,1) + ZV(5,1,1))

REM----- Corner at NPT,0

FX(11,NPT,1) = 9*(XV(2,NPT,1)-XV(3,NPT,1)-XV(6,NPT,1) + XV(7,NPT,1))
FY(11,NPT,1) = 9*(YV(2,NPT,1)-YV(3,NPT,1)-YV(6,NPT,1) + YV(7,NPT,1))
FZ(11,NPT,1) = 9*(ZV(2,NPT,1)-ZV(3,NPT,1)-ZV(6,NPT,1) + ZV(7,NPT,1))

REM----- Corner at 0,NPS

)
FX(14,1,NPS) = 9*(XV(8,1,NPS)-XV(9,1,NPS)-XV(12,1,NPS) + XV(13,1,NPS))
)
FY(14,1,NPS) = 9*(YV(8,1,NPS)-YV(9,1,NPS)-YV(12,1,NPS) + YV(13,1,NPS))
)
FZ(14,1,NPS) = 9*(ZV(8,1,NPS)-ZV(9,1,NPS)-ZV(12,1,NPS) + ZV(13,1,NPS))
)

REM----- Corner at NPT,NPS

K = NPT
L = NPS

FX(15,K,L) = 9*(XV(10,K,L)-XV(11,K,L)-XV(14,K,L) + XV(15,K,L))
FY(15,K,L) = 9*(YV(10,K,L)-YV(11,K,L)-YV(14,K,L) + YV(15,K,L))
FZ(15,K,L) = 9*(ZV(10,K,L)-ZV(11,K,L)-ZV(14,K,L) + ZV(15,K,L))

END IF

REM----- GET CORNERS -----

FOR J = 1 TO JJ-1
 FOR I = 1 TO II-1
 XX(I,J) = XV(0,I,J)
 YY(I,J) = YV(0,I,J)
 ZZ(I,J) = ZV(0,I,J)
 NEXT
 XX(II,J) = XV(3,NPT,J)
 YY(II,J) = YV(3,NPT,J)
 ZZ(II,J) = ZV(3,NPT,J)
NEXT

FOR I = 1 TO II-1
 XX(I,JJ) = XV(12,I,NPS)
 YY(I,JJ) = YV(12,I,NPS)
 ZZ(I,JJ) = ZV(12,I,NPS)
NEXT

XX(II,JJ) = XV(15,NPT,NPS)

FOR I = 1 TO NPT

FX(0,I,J) = XX(I,J)
FX(1,I,J) = XX(I+1,J)
FX(4,I,J) = XX(I,J+1)
FX(5,I,J) = XX(I+1,J+1)

FY(0,I,J) = YY(I,J)
FY(1,I,J) = YY(I+1,J)
FY(4,I,J) = YY(I,J+1)
FY(5,I,J) = YY(I+1,J+1)

FZ(0,I,J) = ZZ(I,J)
FZ(1,I,J) = ZZ(I+1,J)
FZ(4,I,J) = ZZ(I,J+1)
FZ(5,I,J) = ZZ(I+1,J+1)

NEXT
NEXT

REM----- GET PC SPLINES THROUGH THE DATA -----

REM----- T-LINES (I-DIRECTION)

CASE\$ = "BEZIER"

N = II

FOR J = 1 TO JJ

IF J = JJ THEN

S1X = 3*(XV(13,1,NPS)-XV(12,1,NPS))
S1Y = 3*(YV(13,1,NPS)-YV(12,1,NPS))
S1Z = 3*(ZV(13,1,NPS)-ZV(12,1,NPS))
S2X = 3*(XV(15,NPT,NPS)-XV(14,NPT,NPS))
S2Y = 3*(YV(15,NPT,NPS)-YV(14,NPT,NPS))
S2Z = 3*(ZV(15,NPT,NPS)-ZV(14,NPT,NPS))

ELSE

S1X = 3*(XV(1,1,J)-XV(0,1,J))
S1Y = 3*(YV(1,1,J)-YV(0,1,J))
S1Z = 3*(ZV(1,1,J)-ZV(0,1,J))
S2X = 3*(XV(3,NPT,J)-XV(2,NPT,J))
S2Y = 3*(YV(3,NPT,J)-YV(2,NPT,J))
S2Z = 3*(ZV(3,NPT,J)-ZV(2,NPT,J))

END IF

FOR I = 1 TO II

X(I) = XX(I,J)
Y(I) = YY(I,J)
Z(I) = ZZ(I,J)

NEXT

GOSUB 1000

FOR I = 1 TO II-1

IF J = 1 GOTO 68

FX(6,I,J-1) = CX(I)
FY(6,I,J-1) = CY(I)
FZ(6,I,J-1) = CZ(I)

FX(7,I,J-1) = 3*AX(I) + 2*BX(I) + CX(I)
FY(7,I,J-1) = 3*AY(I) + 2*BY(I) + CY(I)

```

FX(2,I,J) = CX(I)
FY(2,I,J) = CY(I)
FZ(2,I,J) = CZ(I)

FX(3,I,J) = 3*AX(I) + 2*BX(I) + CX(I)
FY(3,I,J) = 3*AY(I) + 2*BY(I) + CY(I)
FZ(3,I,J) = 3*AZ(I) + 2*BZ(I) + CZ(I)

```

70

NEXT

NEXT

REM----- S-LINES (J-DIRECTION)

CASE\$ = "BEZIER"

N = JJ

FOR I = 1 TO II

IF I = II THEN

```

S1X = 3*(XV(7,NPT,1)-XV(3,NPT,1))
S1Y = 3*(YV(7,NPT,1)-YV(3,NPT,1))
S1Z = 3*(ZV(7,NPT,1)-ZV(3,NPT,1))
S2X = 3*(XV(15,NPT,NPS)-XV(11,NPT,NPS))
S2Y = 3*(YV(15,NPT,NPS)-YV(11,NPT,NPS))
S2Z = 3*(ZV(15,NPT,NPS)-ZV(11,NPT,NPS))

```

ELSE

```

S1X = 3*(XV(4,I,1)-XV(0,I,1))
S1Y = 3*(YV(4,I,1)-YV(0,I,1))
S1Z = 3*(ZV(4,I,1)-ZV(0,I,1))
S2X = 3*(XV(12,I,NPS)-XV(8,I,NPS))
S2Y = 3*(YV(12,I,NPS)-YV(8,I,NPS))
S2Z = 3*(ZV(12,I,NPS)-ZV(8,I,NPS))

```

END IF

FOR J = 1 TO JJ

X(J) = XX(I,J)

Y(J) = YY(I,J)

Z(J) = ZZ(I,J)

NEXT

GOSUB 1000

FOR J = 1 TO JJ-1

IF I = II GOTO 74

```

FX(8,I,J) = CX(J)
FY(8,I,J) = CY(J)
FZ(8,I,J) = CZ(J)

```

```

FX(12,I,J) = 3*AX(J) + 2*BX(J) + CX(J)
FY(12,I,J) = 3*AY(J) + 2*BY(J) + CY(J)
FZ(12,I,J) = 3*AZ(J) + 2*BZ(J) + CZ(J)

```

74

IF I = 1 GOTO 76

```

FX(9,I-1,J) = CX(J)
FY(9,I-1,J) = CY(J)
FZ(9,I-1,J) = CZ(J)

```

```

FX(13,I-1,J) = 3*AX(J) + 2*BX(J) + CX(J)
FY(13,I-1,J) = 3*AY(J) + 2*BY(J) + CY(J)

```

NEXT

REM----- NEXT PUT SPLINES THROUGH THE FIRST DERIVATIVES -----

REM----- PUT SPLINE THROUGH S-DERIV'S ALONG S=0 & S=1 -----

REM----- S=0 (J=1) EDGE

N = II

CASE\$ = "BEZIER"

S1X = FX(10,1,1)

S1Y = FY(10,1,1)

S1Z = FZ(10,1,1)

S2X = FX(11,NPT,1)

S2Y = FY(11,NPT,1)

S2Z = FZ(11,NPT,1)

FOR I = 1 TO NPT

X(I) = FX(8,I,1)

Y(I) = FY(8,I,1)

Z(I) = FZ(8,I,1)

NEXT

X(II) = FX(9,NPT,1)

Y(II) = FY(9,NPT,1)

Z(II) = FZ(9,NPT,1)

GOSUB 1000

FOR I = 1 TO NPT

IF I = 1 GOTO 412

FX(10,I,1) = CX(I)

FY(10,I,1) = CY(I)

FZ(10,I,1) = CZ(I)

412 IF I = NPT GOTO 414

FX(11,I,1) = 3*AX(I) + 2*BX(I) + CX(I)

FY(11,I,1) = 3*AY(I) + 2*BY(I) + CY(I)

FZ(11,I,1) = 3*AZ(I) + 2*BY(I) + CZ(I)

414 NEXT

REM----- S=1 (J=JJ) EDGE

S1X = FX(14,1,NPS)

S1Y = FY(14,1,NPS)

S1Z = FZ(14,1,NPS)

S2X = FX(15,NPT,NPS)

S2Y = FY(15,NPT,NPS)

S2Z = FZ(15,NPT,NPS)

FOR I = 1 TO NPT

NEXT

X(II) = FX(13,NPT,NPS)
Y(II) = FY(13,NPT,NPS)
Z(II) = FZ(13,NPT,NPS)

GOSUB 1000

FOR I = 1 TO NPT

IF I = 1 GOTO 422

FX(14,I,NPS) = CX(I)
FY(14,I,NPS) = CY(I)
FZ(14,I,NPS) = CZ(I)

422 IF I = NPT GOTO 424

FX(15,I,NPS) = 3*AX(I) + 2*BX(I) + CX(I)
FY(15,I,NPS) = 3*AY(I) + 2*BY(I) + CY(I)
FZ(15,I,NPS) = 3*AZ(I) + 2*BZ(I) + CZ(I)

424 NEXT

REM----- NOW SPLINE T-DERIV'S IN S-DIRECTION

FOR I = 1 TO II

IF I = II THEN

S1X = FX(11,NPT,1)
S1Y = FY(11,NPT,1)
S1Z = FZ(11,NPT,1)

S2X = FX(15,NPT,NPS)
S2Y = FY(15,NPT,NPS)
S2Z = FZ(15,NPT,NPS)

ELSE

S1X = FX(10,I,1)
S1Y = FY(10,I,1)
S1Z = FZ(10,I,1)

S2X = FX(14,I,NPS)
S2Y = FY(14,I,NPS)
S2Z = FZ(14,I,NPS)

END IF

FOR J = 1 TO NPS

IF I = II THEN

X(J) = FX(3,NPT,J)
Y(J) = FY(3,NPT,J)
Z(J) = FZ(3,NPT,J)

ELSE

X(J) = FX(2,I,J)
Y(J) = FY(2,I,J)

NEXT

IF I = II THEN

X(JJ) = FX(7,NPT,NPS)
Y(JJ) = FY(7,NPT,NPS)
Z(JJ) = FZ(7,NPT,NPS)

ELSE

X(JJ) = FX(6,I,NPS)
Y(JJ) = FY(6,I,NPS)
Z(JJ) = FZ(6,I,NPS)

END IF

GOSUB 1000

FOR J = 1 TO NPS

IF I = 1 GOTO 432

FX(11,I-1,J) = CX(J)
FY(11,I-1,J) = CY(J)
FZ(11,I-1,J) = CZ(J)

FX(15,I-1,J) = 3*AX(J) + 2*BX(J) + CX(J)
FY(15,I-1,J) = 3*AY(J) + 2*BY(J) + CY(J)
FZ(15,I-1,J) = 3*AZ(J) + 2*BZ(J) + CZ(J)

432 IF I = II GOTO 434

FX(10,I,J) = CX(J)
FY(10,I,J) = CY(J)
FZ(10,I,J) = CZ(J)

FX(14,I,J) = 3*AX(J) + 2*BX(J) + CX(J)
FY(14,I,J) = 3*AY(J) + 2*BY(J) + CY(J)
FZ(14,I,J) = 3*AZ(J) + 2*BZ(J) + CZ(J)

434 NEXT

NEXT

REM----- COMPUTE THE BEZIER CONTROL POINTS -----

DX = .01
DY = .02

FOR JP = 1 TO NPS
FOR IP = 1 TO NPT

REM----- CORNERS

XV(0,IP,JP) = XX(IP,JP)
YV(0,IP,JP) = YY(IP,JP)
ZV(0,IP,JP) = ZZ(IP,JP)

XV(3,IP,JP) = XX(IP+1,JP)
YV(3,IP,JP) = YY(IP+1,JP)
ZV(3,IP,JP) = ZZ(IP+1,JP)

XV(15,IP,JP) = XX(IP+1,JP+1)
YV(15,IP,JP) = YY(IP+1,JP+1)
ZV(15,IP,JP) = ZZ(IP+1,JP+1)

REM----- ON SIDE 1 (S=0)

XV(1,IP,JP) = XV(0,IP,JP) + FX(2,IP,JP)/3
YV(1,IP,JP) = YV(0,IP,JP) + FY(2,IP,JP)/3
ZV(1,IP,JP) = ZV(0,IP,JP) + FZ(2,IP,JP)/3

XV(2,IP,JP) = XV(3,IP,JP) - FX(3,IP,JP)/3
YV(2,IP,JP) = YV(3,IP,JP) - FY(3,IP,JP)/3
ZV(2,IP,JP) = ZV(3,IP,JP) - FZ(3,IP,JP)/3

REM----- ON SIDE 2 (S=1)

XV(13,IP,JP) = XV(12,IP,JP) + FX(6,IP,JP)/3
YV(13,IP,JP) = YV(12,IP,JP) + FY(6,IP,JP)/3
ZV(13,IP,JP) = ZV(12,IP,JP) + FZ(6,IP,JP)/3

XV(14,IP,JP) = XV(15,IP,JP) - FX(7,IP,JP)/3
YV(14,IP,JP) = YV(15,IP,JP) - FY(7,IP,JP)/3
ZV(14,IP,JP) = ZV(15,IP,JP) - FZ(7,IP,JP)/3

REM----- ON SIDE 3 (T=0)

XV(4,IP,JP) = XV(0,IP,JP) + FX(8,IP,JP)/3
YV(4,IP,JP) = YV(0,IP,JP) + FY(8,IP,JP)/3
ZV(4,IP,JP) = ZV(0,IP,JP) + FZ(8,IP,JP)/3

XV(8,IP,JP) = XV(12,IP,JP) - FX(12,IP,JP)/3
YV(8,IP,JP) = YV(12,IP,JP) - FY(12,IP,JP)/3
ZV(8,IP,JP) = ZV(12,IP,JP) - FZ(12,IP,JP)/3

REM----- ON SIDE 4 (T=1)

XV(7,IP,JP) = XV(3,IP,JP) + FX(9,IP,JP)/3
YV(7,IP,JP) = YV(3,IP,JP) + FY(9,IP,JP)/3
ZV(7,IP,JP) = ZV(3,IP,JP) + FZ(9,IP,JP)/3

XV(11,IP,JP) = XV(15,IP,JP) - FX(13,IP,JP)/3
YV(11,IP,JP) = YV(15,IP,JP) - FY(13,IP,JP)/3
ZV(11,IP,JP) = ZV(15,IP,JP) - FZ(13,IP,JP)/3

REM----- INTERIOR POINTS

REM----- POINT 5

XST = FX(10,IP,JP)
YST = FY(10,IP,JP)
ZST = FZ(10,IP,JP)

XV(5,IP,JP) = XV(1,IP,JP) + XV(4,IP,JP) - XV(0,IP,JP) + XST/9
YV(5,IP,JP) = YV(1,IP,JP) + YV(4,IP,JP) - YV(0,IP,JP) + YST/9
ZV(5,IP,JP) = ZV(1,IP,JP) + ZV(4,IP,JP) - ZV(0,IP,JP) + ZST/9

REM----- POINT 6

XST = FX(11,IP,JP)
YST = FY(11,IP,JP)
ZST = FZ(11,IP,JP)

REM----- POINT 9

XST = FX(14,IP,JP)
YST = FY(14,IP,JP)
ZST = FZ(14,IP,JP)

XV(9,IP,JP) = XV(8,IP,JP) + XV(13,IP,JP) - XV(12,IP,JP) - XST/9
YV(9,IP,JP) = YV(8,IP,JP) + YV(13,IP,JP) - YV(12,IP,JP) - YST/9
ZV(9,IP,JP) = ZV(8,IP,JP) + ZV(13,IP,JP) - ZV(12,IP,JP) - ZST/9

REM----- POINT 10

XST = FX(15,IP,JP)
YST = FY(15,IP,JP)
ZST = FZ(15,IP,JP)

XV(10,IP,JP) = XV(11,IP,JP) + XV(14,IP,JP) - XV(15,IP,JP) + XST/9
YV(10,IP,JP) = YV(11,IP,JP) + YV(14,IP,JP) - YV(15,IP,JP) + YST/9
ZV(10,IP,JP) = ZV(11,IP,JP) + ZV(14,IP,JP) - ZV(15,IP,JP) + ZST/9

NEXT
NEXT

990 REM----- THAT'S ALL -----

END

1000 REM----- PC SPLINE SUBROUTINE -----

REM
REM This subroutine takes the N coordinates in the arrays
REM X,Y,and Z,and generates the coefficients AX,BX,CX,AY,
REM BY,CY,AZ,BZ,CZ of the corresponding cubic spline through
REM the data.

REM
REM-----
REM----- SET UP MATRIX -----

FOR KKK = 1 TO ND

FOR IT = 2 TO N-2
C(IT) = 1
B(IT) = 4
A(IT) = 1
NEXT

REM----- RHS

X(0) = X(N): Y(0) = Y(N): Z(0) = Z(N)

FOR IT = 1 TO N-1
IF KKK = 1 THEN
DD = X(IT + 1) - 2*X(IT) + X(IT-1)
ELSEIF KKK = 2 THEN
DD = Y(IT + 1) - 2*Y(IT) + Y(IT-1)
ELSE
DD = Z(IT + 1) - 2*Z(IT) + Z(IT-1)
END IF
D(IT) = 3*DD
NEXT

REM----- CASE\$ = "NATURAL" -----

```

      C(N-1) = 1
      B(N-1) = 4
      GOTO 2040
END IF

```

```

REM----- CASE$ = "BEZIER" -----

```

```

IF CASE$ = "BEZIER" THEN
  B(1) = 2/3
  A(1) = 1/3
  B(N-1) = 7/3
  C(N-1) = 2/3
  IF KKK = 1 THEN
    D(1) = (X(2)-X(1))-S1X
    D(N-1) = 3*(X(N)-X(N-1))-2*(X(N-1)-X(N-2))-S2X
  ELSEIF KKK = 2 THEN
    D(1) = (Y(2)-Y(1))-S1Y
    D(N-1) = 3*(Y(N)-Y(N-1))-2*(Y(N-1)-Y(N-2))-S2Y
  ELSE
    D(1) = (Z(2)-Z(1))-S1Z
    D(N-1) = 3*(Z(N)-Z(N-1))-2*(Z(N-1)-Z(N-2))-S2Z
  END IF

```

```

END IF

```

```

2040 REM----- SOLVE MATRIX -----

```

```

      GOSUB 2000

```

```

REM----- NOW GET COEFFS -----

```

```

IF KKK = 1 THEN
  FOR IT = 1 TO N-1
    BX(IT) = D(IT)
  NEXT
  FOR IT = 1 TO N-2
    AX(IT) = (BX(IT + 1)-BX(IT))/3
    CX(IT) = X(IT + 1)-X(IT)-AX(IT)-BX(IT)
  NEXT
  CX(N-1) = 3*AX(N-2) + 2*BX(N-2) + CX(N-2)
  AX(N-1) = X(N)-BX(N-1)-CX(N-1)-X(N-1)
ELSEIF KKK = 2 THEN
  FOR IT = 1 TO N-1
    BY(IT) = D(IT)
  NEXT
  FOR IT = 1 TO N-2
    AY(IT) = (BY(IT + 1)-BY(IT))/3
    CY(IT) = Y(IT + 1)-Y(IT)-AY(IT)-BY(IT)
  NEXT
  CY(N-1) = 3*AY(N-2) + 2*BY(N-2) + CY(N-2)
  AY(N-1) = Y(N)-BY(N-1)-CY(N-1)-Y(N-1)
ELSE
  FOR IT = 1 TO N-1
    BZ(IT) = D(IT)
  NEXT
  FOR IT = 1 TO N-2
    AZ(IT) = (BZ(IT + 1)-BZ(IT))/3
    CZ(IT) = Z(IT + 1)-Z(IT)-AZ(IT)-BZ(IT)
  NEXT
  CZ(N-1) = 3*AZ(N-2) + 2*BZ(N-2) + CZ(N-2)
  AZ(N-1) = Z(N)-BZ(N-1)-CZ(N-1)-Z(N-1)
END IF

```

2000 REM----- SUBROUTINE TSOLV -----

FOR IT = 2 TO N-1

 CBI = C(IT)/B(IT-1)

 B(IT) = B(IT)-CBI*A(IT-1)

 D(IT) = D(IT)-CBI*D(IT-1)

NEXT

D(N-1) = D(N-1)/B(N-1)

FOR IR = 1 TO N-2

 IT = N-IR-1

 D(IT) = (D(IT)-A(IT)*D(IT + 1))/B(IT)

NEXT

RETURN